

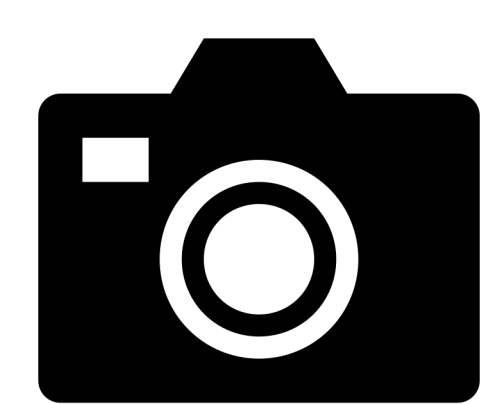


Leveraging Cloud Computing to Make Autonomous Vehicles Safer

Peter Schafhalter, Sukrit Kalra, Le Xu, Joseph E. Gonzalez, Ion Stoica

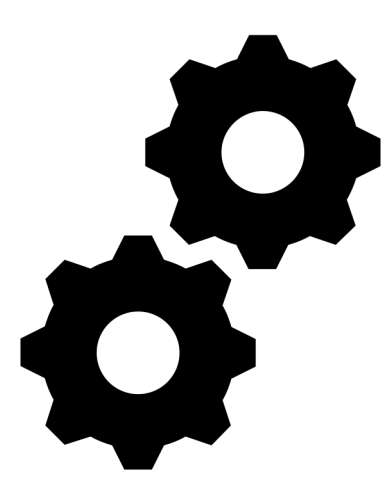


AVs need:



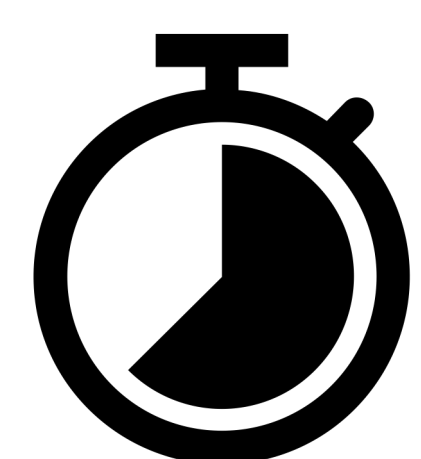
High-fidelity data:

Better information for decision-making



State-of-the-art computation:

Want to run the most accurate models.

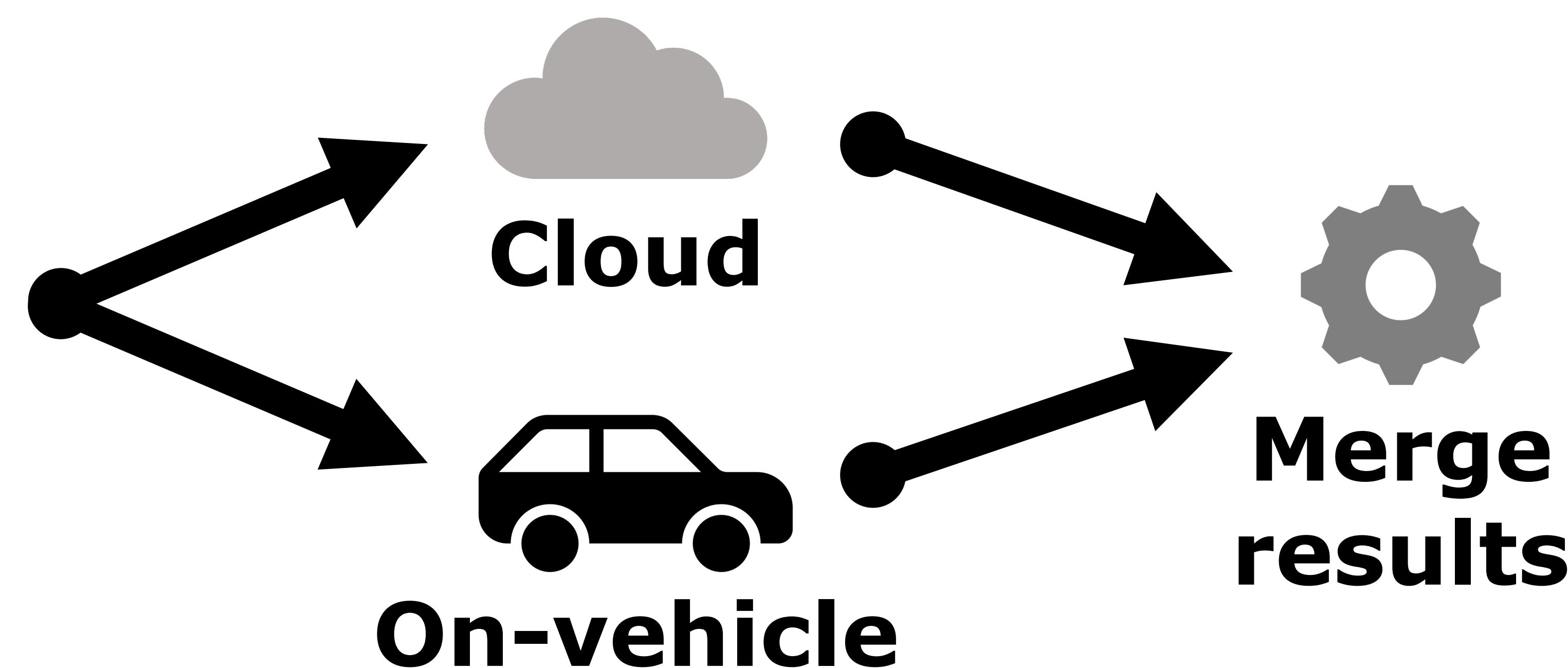


Timely results:

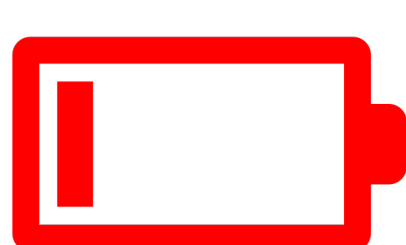
Run in real-time to beat human reaction times.

AVs should use the cloud!

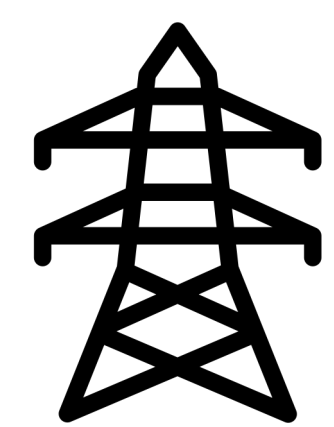
- Large pool of powerful resources
- 5G networks are good enough
- Use speculative execution to ensure reliability



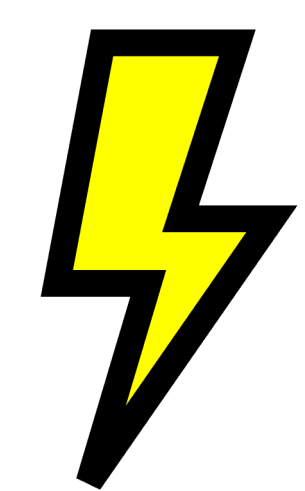
Hardware



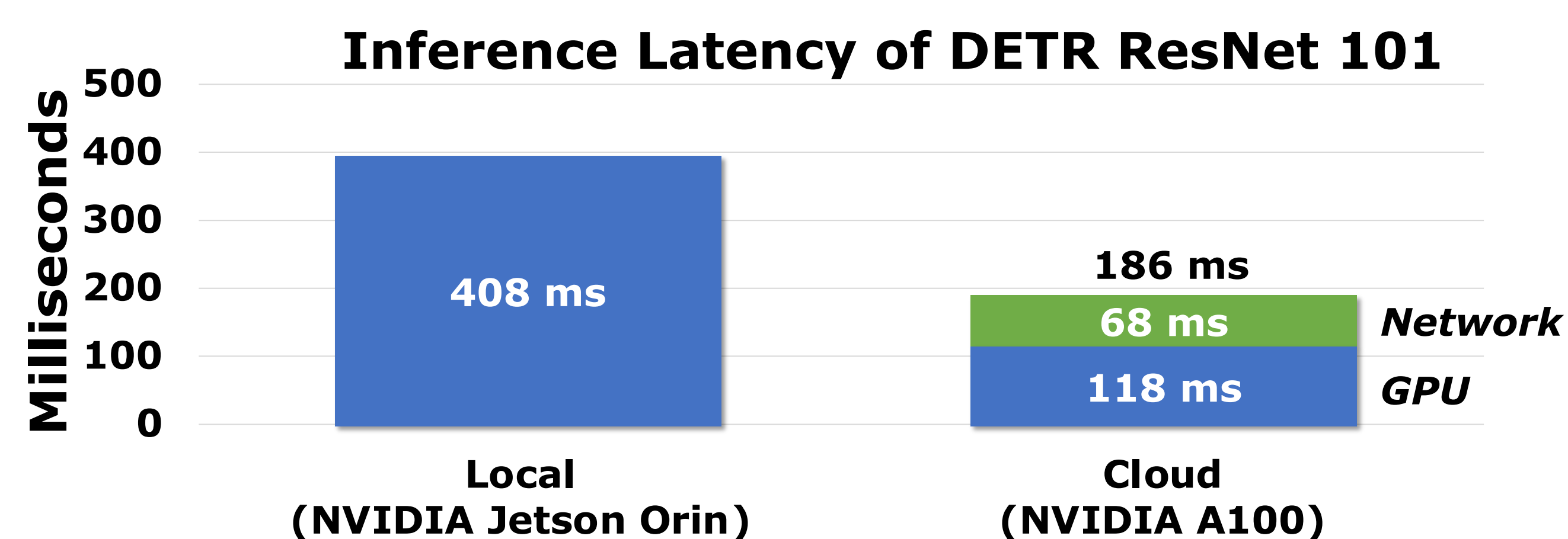
Limited in AVs due to physical constraints: power, cooling, stability.



Plentiful in the cloud: Specialized datacenters, frequent H/W upgrades.

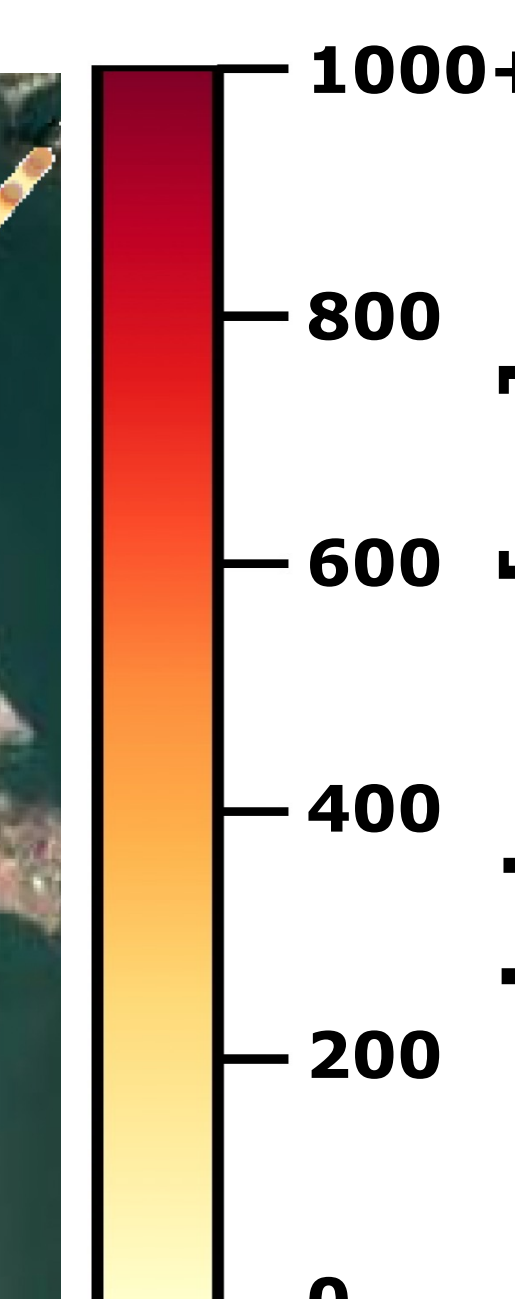


Powerful cloud H/W: can run highly accurate models in real time.



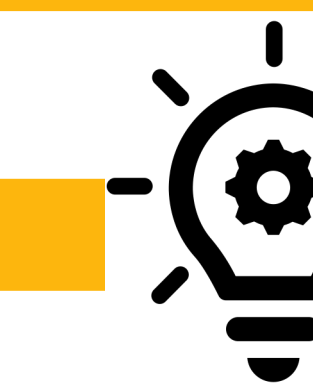
Network

Modeled transmission of HD camera footage over 5G from car to cloud.



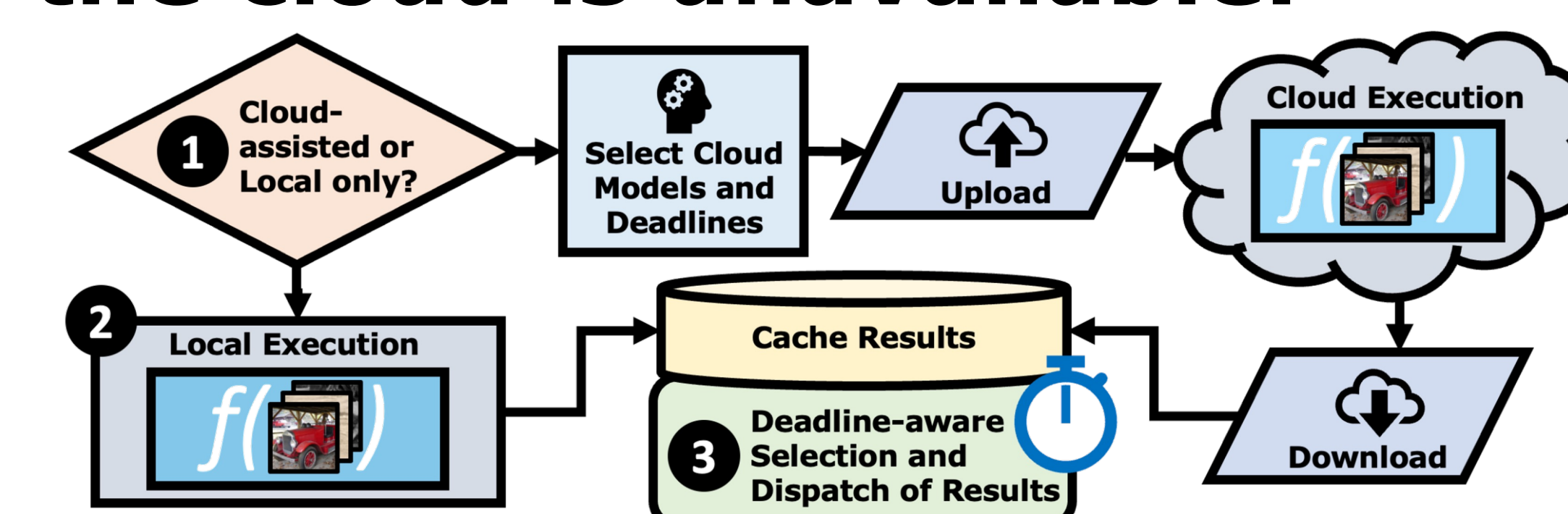
Round-trip latency:

- Fast
- Median: 68 ms
- Unreliable
- 99th percentile: 3027 ms



Design

- 1 Speculatively execute in cloud.
- 2 In parallel, run locally.
- 3 Fall back to local results when the cloud is unavailable.



Read the paper



tinyurl.com/cloud-avs



Contact

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